

Since we have been dealing with the problem of various definitions of subnet in literature, I have gathered here at least some of them.

## Definitions

### Subnet defined using cofinal map

Engelking [E]:

**Definition 1.** We say that the net  $S' = \{x_{\sigma'}, \sigma' \in \Sigma'\}$  is *finer* than the net  $S = \{x_{\sigma}, \sigma \in \Sigma\}$  if there exists a function  $\varphi$  of  $\Sigma'$  to  $\Sigma$  with following properties:

- (i) For every  $\sigma_0 \in \Sigma$  there exists a  $\sigma'_0 \in \Sigma'$  such that  $\varphi(\sigma') \geq \sigma_0$  whenever  $\sigma' \geq \sigma'_0$ .
- (ii)  $x_{\varphi(\sigma')} = x_{\sigma'}$  for  $\sigma' \in \Sigma'$ .

A point  $x$  is called a *cluster point of a net*  $S = \{x_{\sigma}, \sigma \in \Sigma\}$  if for every  $\sigma_0 \in \Sigma$  there exists a  $\sigma \geq \sigma_0$  such that  $x_{\sigma} \in U$ .

[K] has the same definition, the only difference is using the term *subnet* instead of finer net of [E]. He also mentions that: “Notice that each cofinal subset  $E$  of  $D$  is directed by the same ordering, and that  $\{S_n, n \in E\}$  is a subnet of  $S$ . (Let  $N$  be the identity function on  $E$ , and the second condition of the definition becomes the requirement that  $E$  be cofinal.) This is a standard way of constructing subnets, and it is unfortunate that this simple variety of subnet is not adequate for all purposes. (2.E)”

The same definition is also used in [AB, Definition 2.15], [P, 1.3.2], [Dud, p.48], [BvR, p.206].

Pedersen’s book [P] contains also the following note: “In most cases we can choose  $h$  to be monotone, and then, in order to have a subnet, it suffices to check that for each  $\lambda$  in  $\Lambda$ , there is a  $\mu$  in  $M$  with  $\lambda \leq h(\mu)$ .”

Dudley [Dud] uses the term *strict subnet* – I am not sure, but by “nonstrict subnet” he probably means a subnet given by a cofinal subset of directed set.

This definition is reformulated using the notion of cofinal map as follows:

**Definition 2.** [[R, Definition 3.3.13]] Let  $\mathbb{A}$  and  $\mathbb{B}$  be directed sets. A map  $\phi: \mathbb{B} \rightarrow \mathbb{A}$  is called *cofinal* if, for each  $\alpha \in \mathbb{A}$  there is  $\beta_{\alpha} \in \mathbb{B}$  such that  $\alpha \preceq \phi(\beta)$  for all  $\beta \in \mathbb{B}$  such that  $\beta_{\alpha} \preceq \beta$ .

**Definition 3.** [[R, Definition 3.3.14]] Let  $S$  be a non-empty set, and let  $(x_{\alpha})_{\alpha \in \mathbb{A}}$  and  $(y_{\beta})_{\beta \in \mathbb{B}}$  be nets in  $S$ . Then  $(y_{\beta})_{\beta \in \mathbb{B}}$  is a subnet of  $(x_{\alpha})_{\alpha \in \mathbb{A}}$  if  $y_{\beta} = x_{\phi(\beta)}$  for a cofinal map  $\phi: \mathbb{B} \rightarrow \mathbb{A}$ .

In [Gä] we can find still another definition using the section filter. Let  $J$  and  $I$  be directed sets,  $\mathfrak{K}$  and  $\mathfrak{L}$  be the corresponding filter.  $(y_j)_J$  is said to be *subnet* (*Teilnetz*) of  $(x_i)_I$  if there exists a map  $f: J \rightarrow I$  such that  $x_{f(i)} = y_i$  for each  $i \in J$  and  $\mathfrak{K} \subseteq f(\mathfrak{L})$  (i.e., for each  $K \in \mathfrak{K}$  there exists  $L \in \mathfrak{L}$  with  $f[L] \subseteq K$ .)

Again, this is an equivalent definition to Definition 1. This shows (in my opinion) the connection between the notion of a subnet and the notion of finer filter.

Summary: Definition 1 (or an equivalent definition) in [AB, BvR, Dud, E, Gä, K, R, P]. (Cofinal map is mentioned explicitly only in [R].)

## Subnet defined using increasing cofinal map

Willard [W, Definition 11.2]:

**Definition 4.** A *subnet* of a net  $P: \Lambda \rightarrow X$  is the composition  $P \circ \varphi$ , where  $\varphi: M \rightarrow \Lambda$  is an increasing cofinal function from a directed set  $M$  to  $\Lambda$ . That is,

- (a)  $\varphi(\mu_1) \leq \varphi(\mu_2)$  whenever  $\mu_1 \leq \mu_2$  ( $\varphi$  is *increasing*),
- (b) for each  $\lambda \in \Lambda$ , there is some  $\mu \in M$  such that  $\lambda \leq \varphi(\mu)$  ( $\varphi$  is *cofinal* in  $\Lambda$ ).

Notice that (b) in the preceding definition says that  $\varphi$  has cofinal range, but for monotone maps this is equivalent to Definition 2.

Munkres [M, p.188]:  $i \leq j \Rightarrow g(i) \leq g(j)$  and  $g[K]$  is cofinal in  $J$ .

The same definition is in [B, p.149] and .

Summary: I found this definition only in [B, Ge, M, W]. (The notion of cofinal map is mentioned explicitly in [W], but the definitions in remaining books are equivalent to this one.)

## Definitions of cofinal map

It is quite common when dealing with ordinals, that cofinal map is defined as a map with cofinal range. (This can be found in various set theoretic textbooks, as Tourlakis: Lectures in logic and set theory, vol. 2; Ciesielski: Set Theory for the Working Mathematician, probably also some other books.) But here we deal only with functions from ordinals to ordinals (i.e., linearly ordered sets) which is a different situation. And again in this case, the first thing these authors do is showing that if there is a cofinal increasing function from an ordinal  $\alpha$  to a ordinal  $\beta$ , then there exists a cofinal order-preserving map.

## Various names for upper section and cofinal subsets

section: terminal set in [Dug]

cofinal subset:

cofinal map:

section filter: zu  $\preceq$  gehörige Filter in [Gä]

## Are these definitions “compatible”?

### Cluster points

TODO

## References

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